

# Introduction to C/C++ code generation from MATLAB code with MATLAB Coder

Generating **readable** and **portable** C/C++ code from your MATLAB algorithms

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# Agenda

- Motivation
  - Why translate MATLAB to C/C++?
  - Challenges of manual translation
- Using MATLAB Coder
  - Three-step workflow for generating code
- Use cases
  - Integrate algorithms using source code/libraries
  - Accelerate through MEX
  - Prototype by generating EXE
- Conclusion
  - Integration with Simulink, Embedded Coder, and GPU Coder
  - Other deployment solutions

# Why Engineers Translate MATLAB to C/C++ Today



.c/cpp

**Implement** C/C++ code on processors or hand off to software engineers



.lib  
.dll

**Integrate** MATLAB algorithms with existing C/C++ environment using source code and static/dynamic libraries



.exe

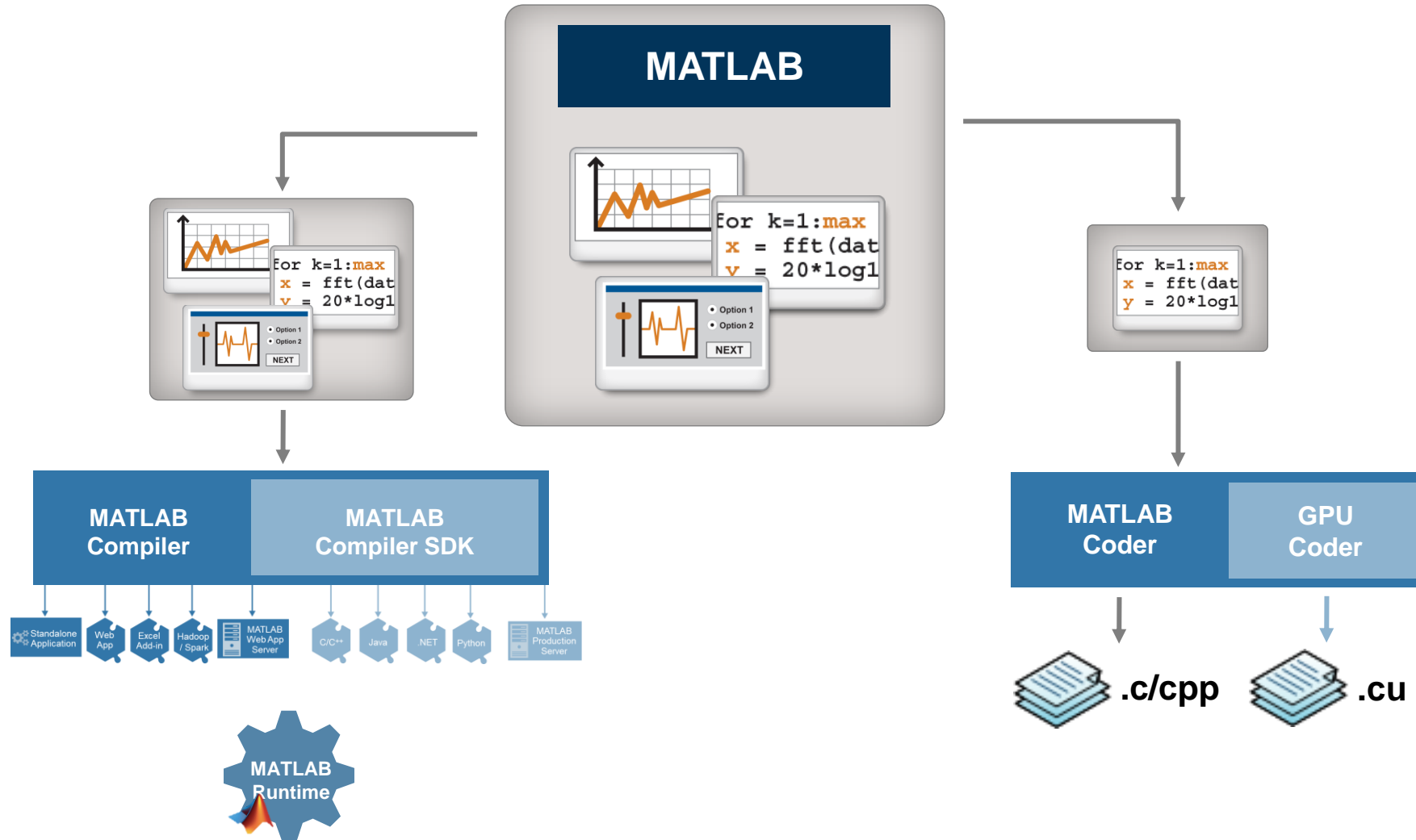
**Prototype** MATLAB algorithms on desktops as standalone executables



MEX

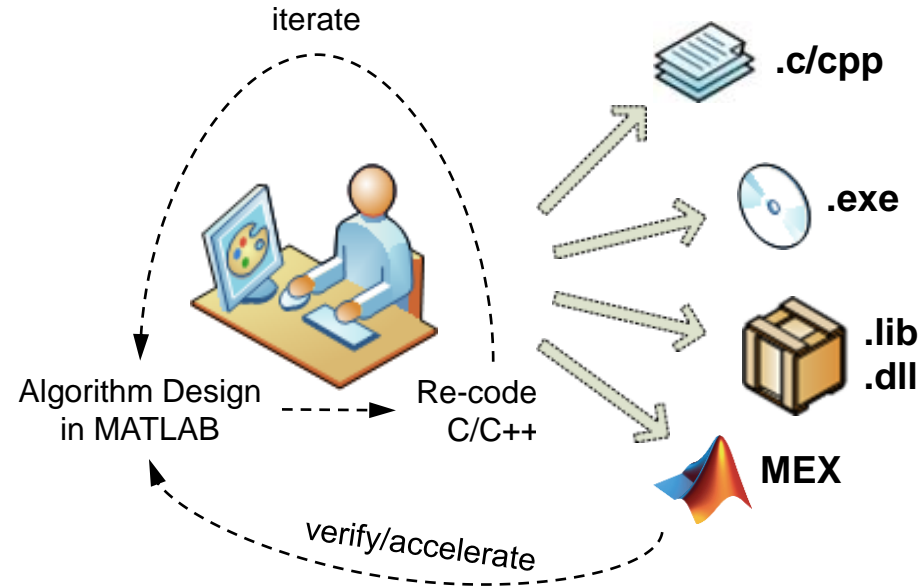
**Accelerate** user-written MATLAB algorithms

# Deploying MATLAB Algorithms



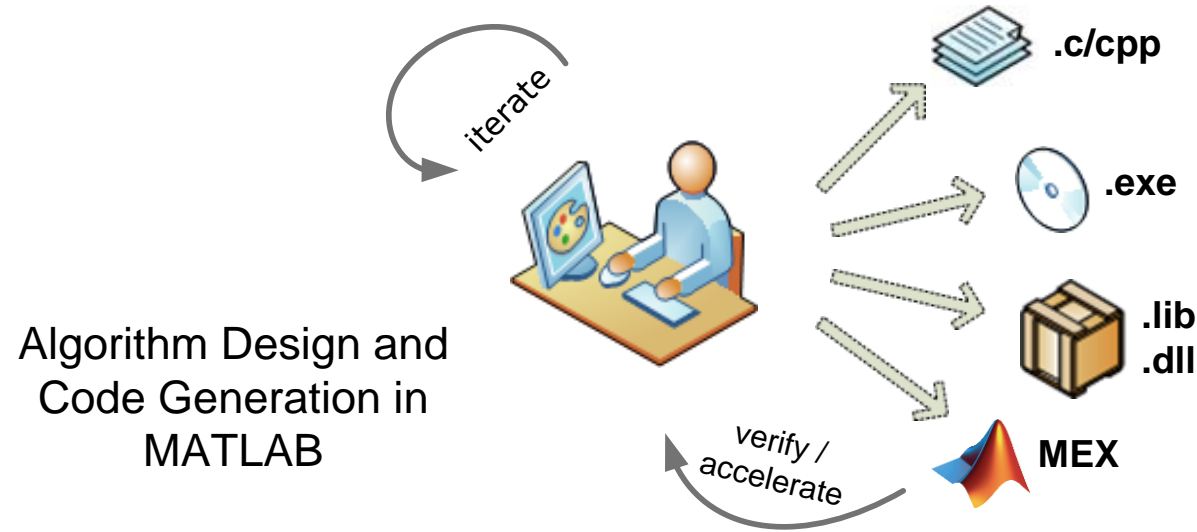
# Challenges with Manual Translation

## from MATLAB to C/C++



- Separate functional and implementation specification
  - Leads to multiple implementations that are inconsistent
  - Hard to modify requirements during development
  - Difficult to keep reference MATLAB code and C/C++ code in sync
- Manual coding errors
- Time-consuming and expensive process

# Automatic Translation of MATLAB to C/C++

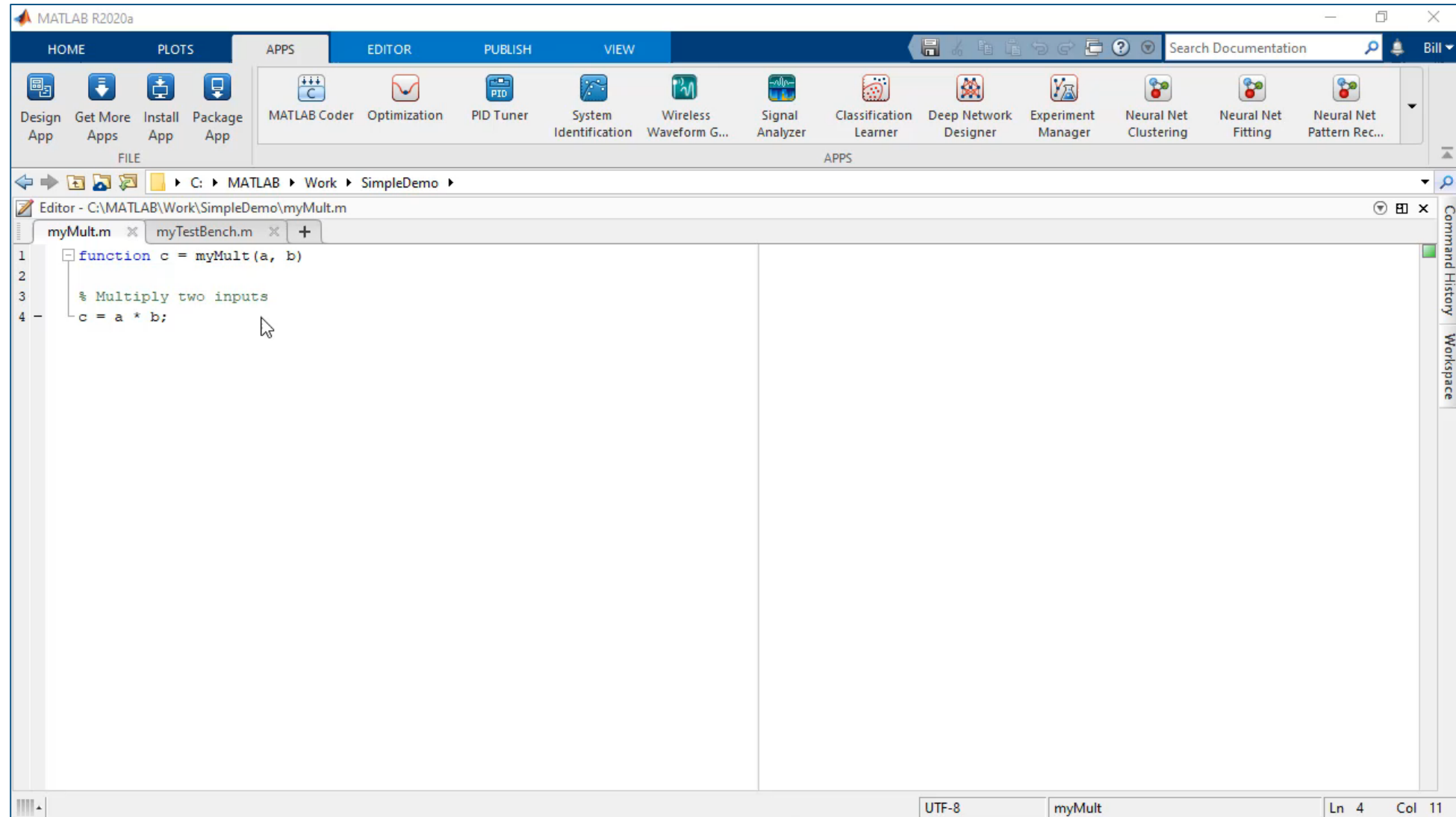


## With MATLAB Coder, design engineers can:

- Maintain one design in MATLAB
- Design faster and get to C/C++ quickly
- Test more systematically and frequently
- Spend more time improving algorithms in MATLAB

# Simple Example

$c = a * b$



Design  
AppGet More  
AppsInstall  
AppPackage  
App

MATLAB Coder



Optimization



PID Tuner

System  
IdentificationWireless  
Waveform G...Signal  
AnalyzerClassification  
LearnerDeep Network  
DesignerExperiment  
ManagerNeural Net  
ClusteringNeural Net  
FittingNeural Net  
Pattern Rec...

FILE

APPS

 C:\MATLAB\Work\SimpleDemo

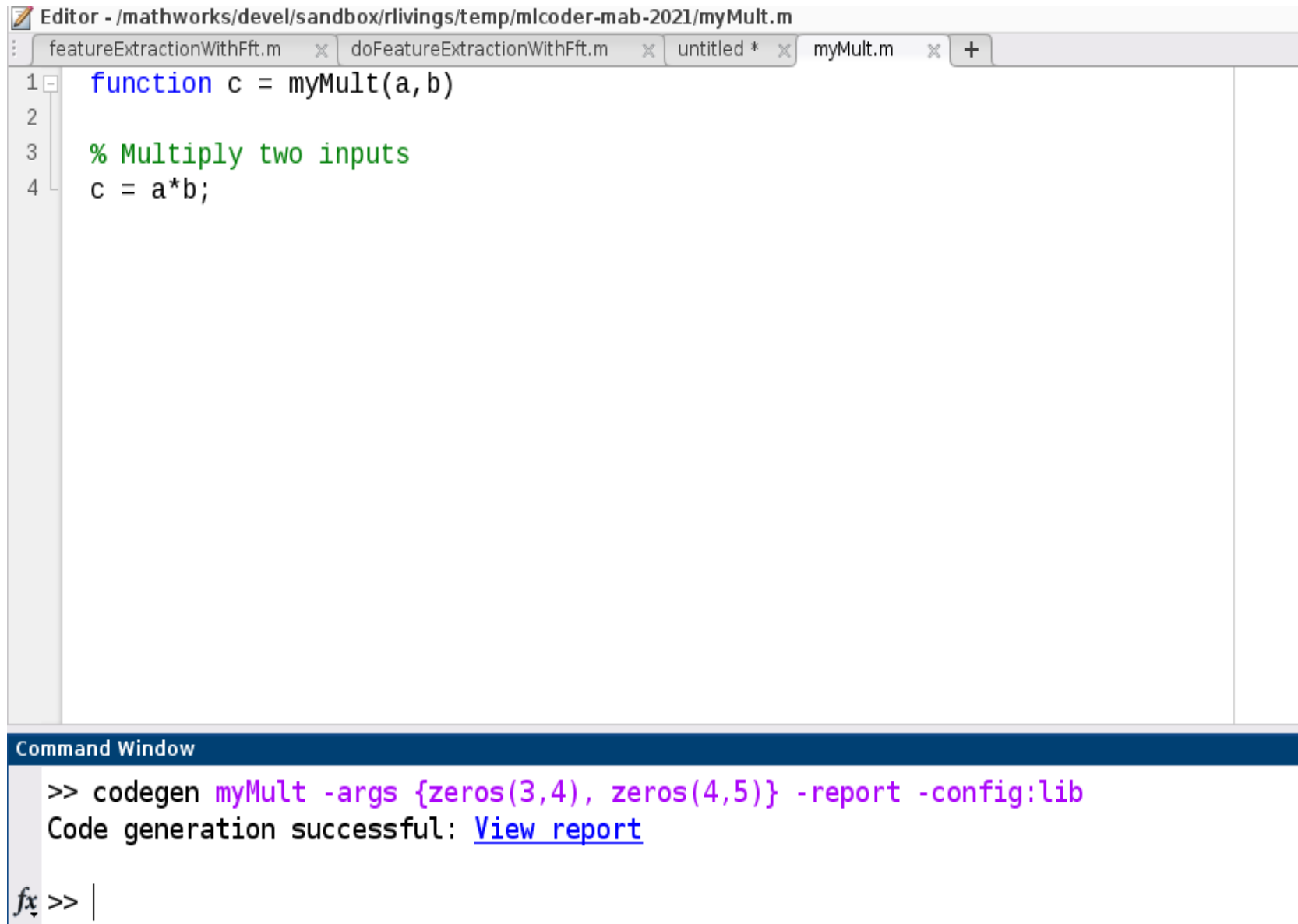
Editor - C:\MATLAB\Work\SimpleDemo\myMult.m

myMult.m x myTestBench.m x +

```
1 function c = myMult(a, b)
2
3     % Multiply two inputs
4     c = a * b;
```



# Command-line Code Generation



The image shows a MATLAB Editor window with the title bar "/mathworks/devel/sandbox/rlivings/temp/mlcoder-mab-2021/myMult.m". The editor contains the following code:

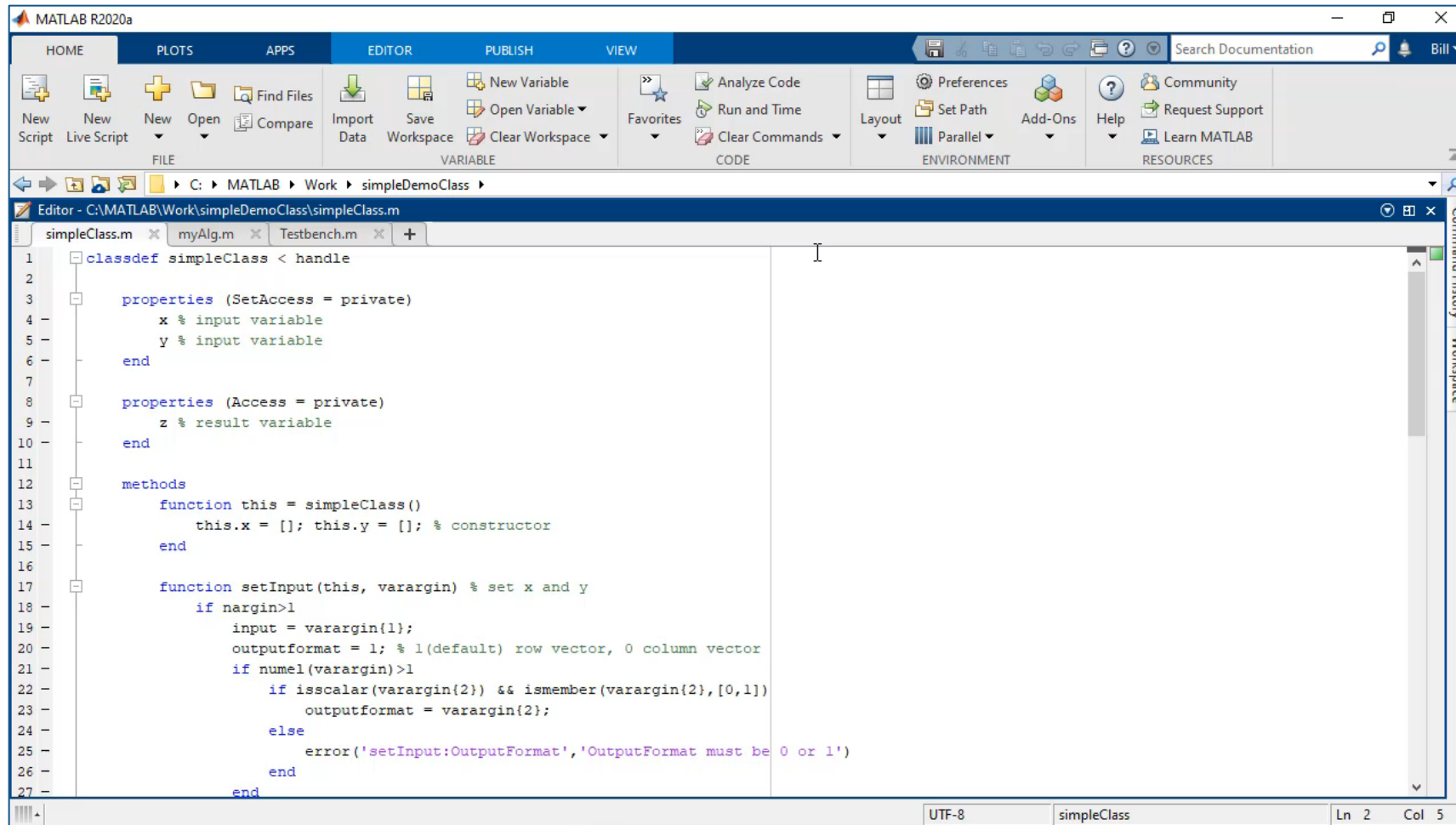
```
1 function c = myMult(a,b)
2
3 % Multiply two inputs
4 c = a*b;
```

Below the editor is the Command Window, which displays the following command and output:

```
>> codegen myMult -args {zeros(3,4), zeros(4,5)} -report -config:lib
Code generation successful: View report
```

The Command Window prompt is `fx >> |`.

# MATLAB Class to C++ Class Example



The image shows the MATLAB R2020a Editor window with the file `simpleClass.m` open. The class is defined as follows:

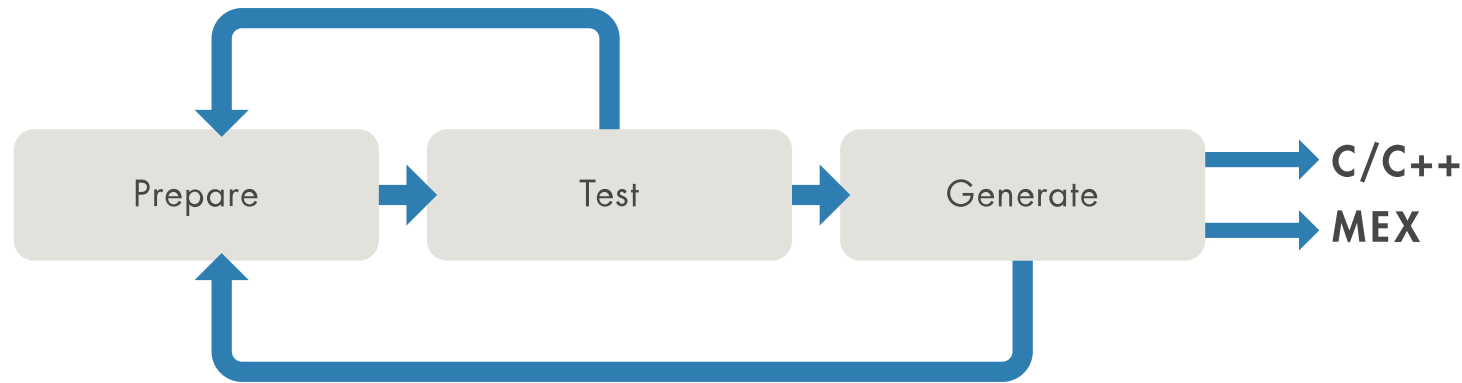
```
1 classdef simpleClass < handle
2
3     properties (SetAccess = private)
4         x % input variable
5         y % input variable
6     end
7
8     properties (Access = private)
9         z % result variable
10    end
11
12    methods
13        function this = simpleClass()
14            this.x = []; this.y = []; % constructor
15        end
16
17        function setInput(this, varargin) % set x and y
18            if nargin>1
19                input = varargin{1};
20                outputformat = 1; % 1(default) row vector, 0 column vector
21                if numel(varargin)>1
22                    if isscalar(varargin{2}) && ismember(varargin{2},[0,1])
23                        outputformat = varargin{2};
24                    else
25                        error('setInput:OutputFormat','OutputFormat must be 0 or 1')
26                    end
27                end
28            end
29        end
30    end
31 end
```

The status bar at the bottom indicates the file is `simpleClass` in UTF-8 encoding, with the cursor at line 2, column 5.

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# Using MATLAB Coder: Three-Step Workflow



**Prepare** your MATLAB algorithm for code generation

- Make implementation choices
- Use supported language features

**Test** if your MATLAB code is ready for code generation

- Validate that MATLAB program generates code
- Accelerate execution of user-written algorithm

**Generate** source code or MEX for final use

- Iterate your MATLAB code to optimize
- Implement as source, executable, or library

# Implementation Considerations

```
function a= foo(b,c)  
a = b * c;
```

Scalar multiply

Dot product

Matrix multiply

logical  
integer  
real  
complex  
...

**C**

```
double foo(double b, double c)  
{  
    return b*c;  
}
```

```
void foo(const double b[15],  
         const double c[30], double a[18])  
{  
    int i0, i1, i2;  
    for (i0 = 0; i0 < 3; i0++) {  
        for (i1 = 0; i1 < 6; i1++) {  
            a[i0 + 3 * i1] = 0.0;  
            for (i2 = 0; i2 < 5; i2++) {  
                a[i0 + 3 * i1] += b[i0 + 3 * i2] * c[i2 + 5 * i1];  
            }  
        }  
    }  
}
```

# Implementation Considerations

- Polymorphism
- Memory allocation
- Processing matrices and arrays
- Fixed-point data types

**7 Lines of MATLAB**  
**105 Lines of C**

```
function [x_est, p_est] = kalman_estimate(R,H,x_prd,p_prd,z)
S = H * p_prd' * H' + R;
B = H * p_prd';
klm_gain = (S \ B)';
x_est = x_prd + klm_gain * (z - H * x_prd);
p_est = p_prd - klm_gain * H * p_prd;
```

```
#include "kalman_estimate.h"

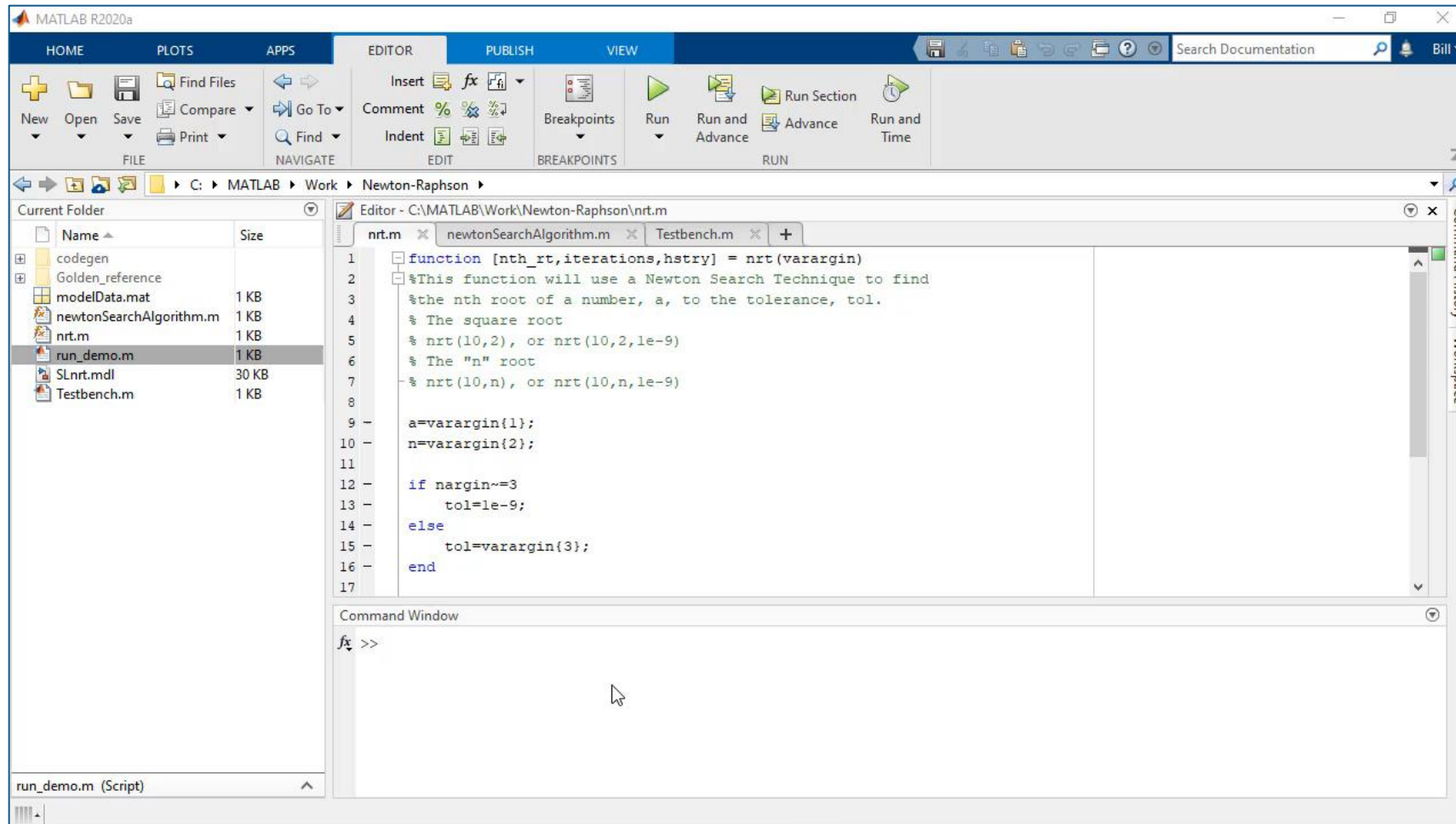
void kalman_estimate(const double R[4], const double H[6], double p[6], double z)
{
    double klm_gain[12];
    int r1;
    int r2;
    int k;
    double S[4];
    double a21;
    double B[12];
    double a22;
    double Y[12];
    double b_z[2];
    double b_klm_gain[36];
    for (r1 = 0; r1 < 2; r1++) {
        for (r2 = 0; r2 < 6; r2++) {
            klm_gain[r1 + (r2 << 1)] = 0.0;
```

```
        for (k = 0; k < 6; k++) {
            klm_gain[r1 + (r2 << 1)] += H[r1 + (k << 1)] *
        }
    }
    for (r1 = 0; r1 < 2; r1++) {
        for (r2 = 0; r2 < 6; r2++) {
            a21 = 0.0;
            for (k = 0; k < 6; k++) {
                a21 += klm_gain[r1 + (r2 << 1)] * H[r1 + (k << 1)];
            }
            S[r1 + (r2 << 1)] = a21;
        }
    }
    a21 = S[2] / S[1];
    a22 = S[2 + 2] - a21 * S[2 + 1];
    for (k = 0; k < 6; k++) {
        Y[1 + (k << 1)] = (B[2 + (k << 1)] - B[1 + (k << 1)] * a21) / a22;
        Y[k << 1] = (B[1 + (k << 1)] - Y[1 + (k << 1)] * S[2 + 1]) / S[1];
    }
```

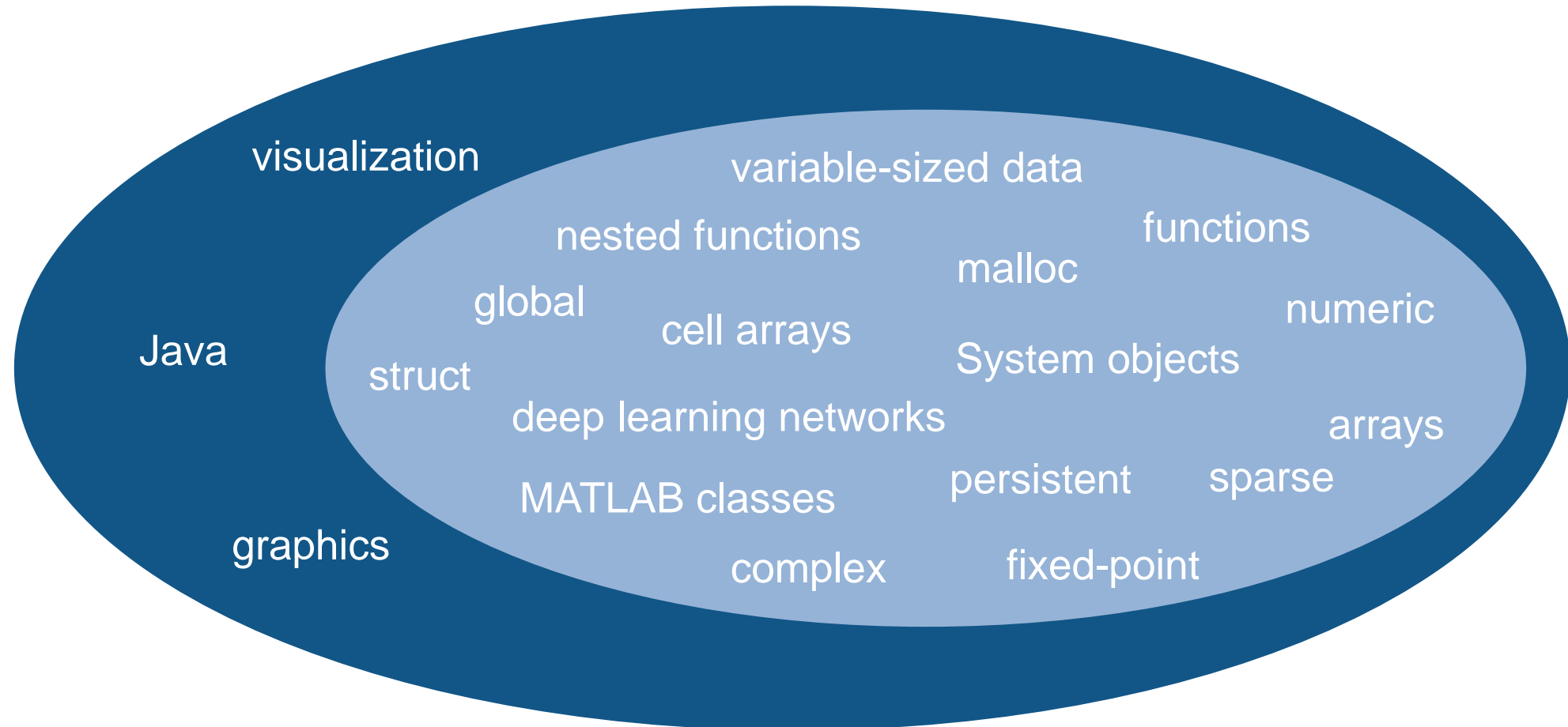
```
    for (r1 = 0; r1 < 2; r1++) {
        for (r2 = 0; r2 < 6; r2++) {
            klm_gain[r2 + 6 * r1] = Y[r1 + (r2 << 1)];
        }
    }
```

```
    for (r1 = 0; r1 < 6; r1++) {
        for (r2 = 0; r2 < 6; r2++) {
            b_klm_gain[r1 + 6 * r2] = 0.0;
            for (k = 0; k < 2; k++) {
                b_klm_gain[r1 + 6 * r2] += klm_gain[r1 + 6 * k] * H[k + (r2 << 1)];
            }
        }
    }
    for (r1 = 0; r1 < 6; r1++) {
        for (r2 = 0; r2 < 6; r2++) {
            a21 = 0.0;
            for (k = 0; k < 6; k++) {
                a21 += b_klm_gain[r1 + 6 * k] * p_prd[k + 6 * r2];
            }
            p_est[r1 + 6 * r2] = p_prd[r1 + 6 * r2] - a21;
        }
    }
```

# Newton/Raphson Example

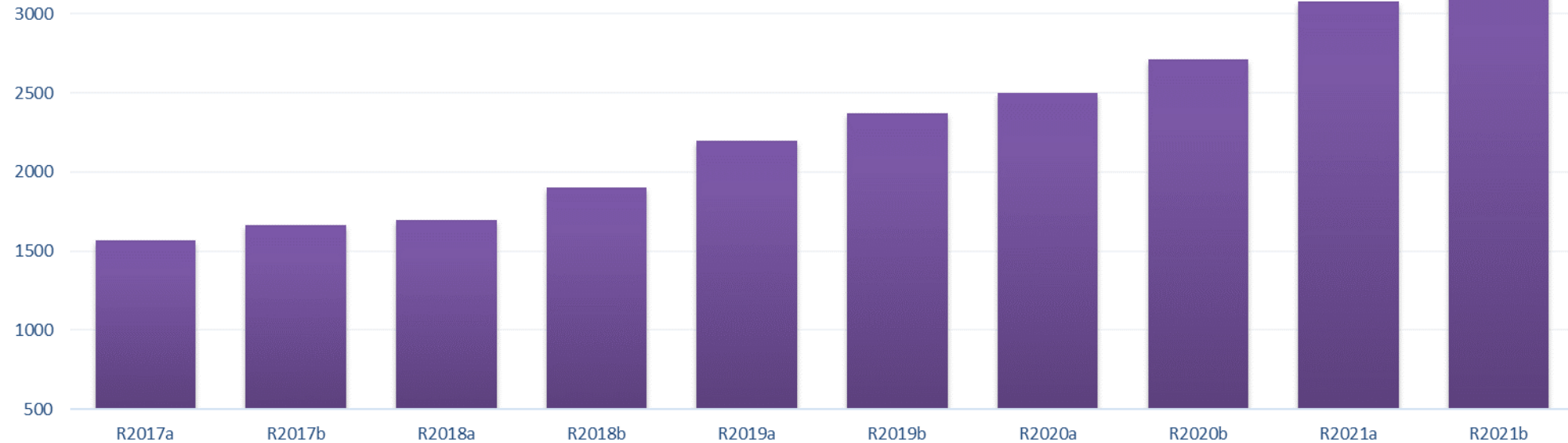


# Growing MATLAB Language Support for Code Generation





# 3250 Functions & 37 Toolboxes Supported



- 5G Toolbox
- Aerospace Toolbox
- Antenna Toolbox
- Audio System Toolbox
- Automated Driving Toolbox
- Communications Toolbox
- Computer Vision Toolbox
- Control System Toolbox
- Deep Learning Toolbox
- DSP System Toolbox
- Fixed-Point Designer
- Fuzzy Logic Toolbox
- Image Acquisition Toolbox
- Image Processing Toolbox
- Instrumental Control Toolbox
- Lidar Toolbox R2021a
- Mapping Toolbox R2021a
- Mixed-Signal Blockset
- Model Predictive Control Toolbox
- Navigation Toolbox
- Optimization Toolbox
- Phased Array System Toolbox
- Predictive Maintenance Toolbox R2021a
- Radar Toolbox R2021a
- Reinforcement Learning Toolbox R2021b
- Robotics System Toolbox
- ROS Toolbox
- Satellite Communications Toolbox
- Sensor Fusion and Tracking Toolbox
- SerDes Toolbox
- Signal Processing Toolbox
- Stats & Machine Learning Toolbox
- System Identification Toolbox
- UAV Toolbox
- Vision HDL Toolbox R2021b
- Wavelet Toolbox
- WLAN System Toolbox

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# MATLAB Coder Use Cases



**Integrate**  
algorithms with custom software



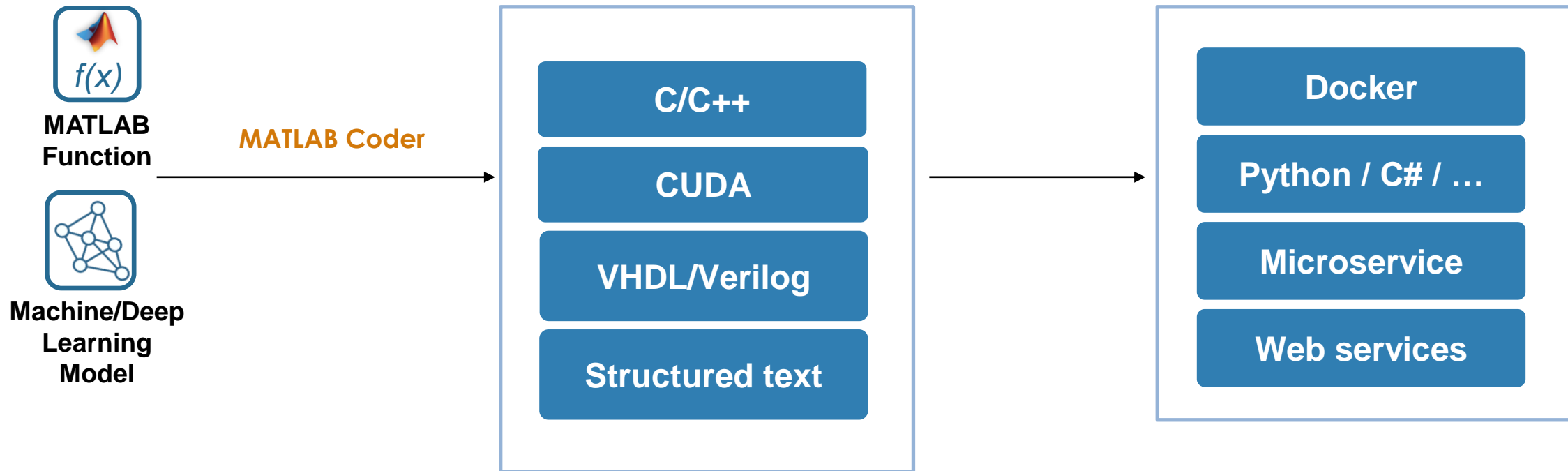
**Prototype**  
algorithms on PCs

**Accelerate**  
algorithm execution

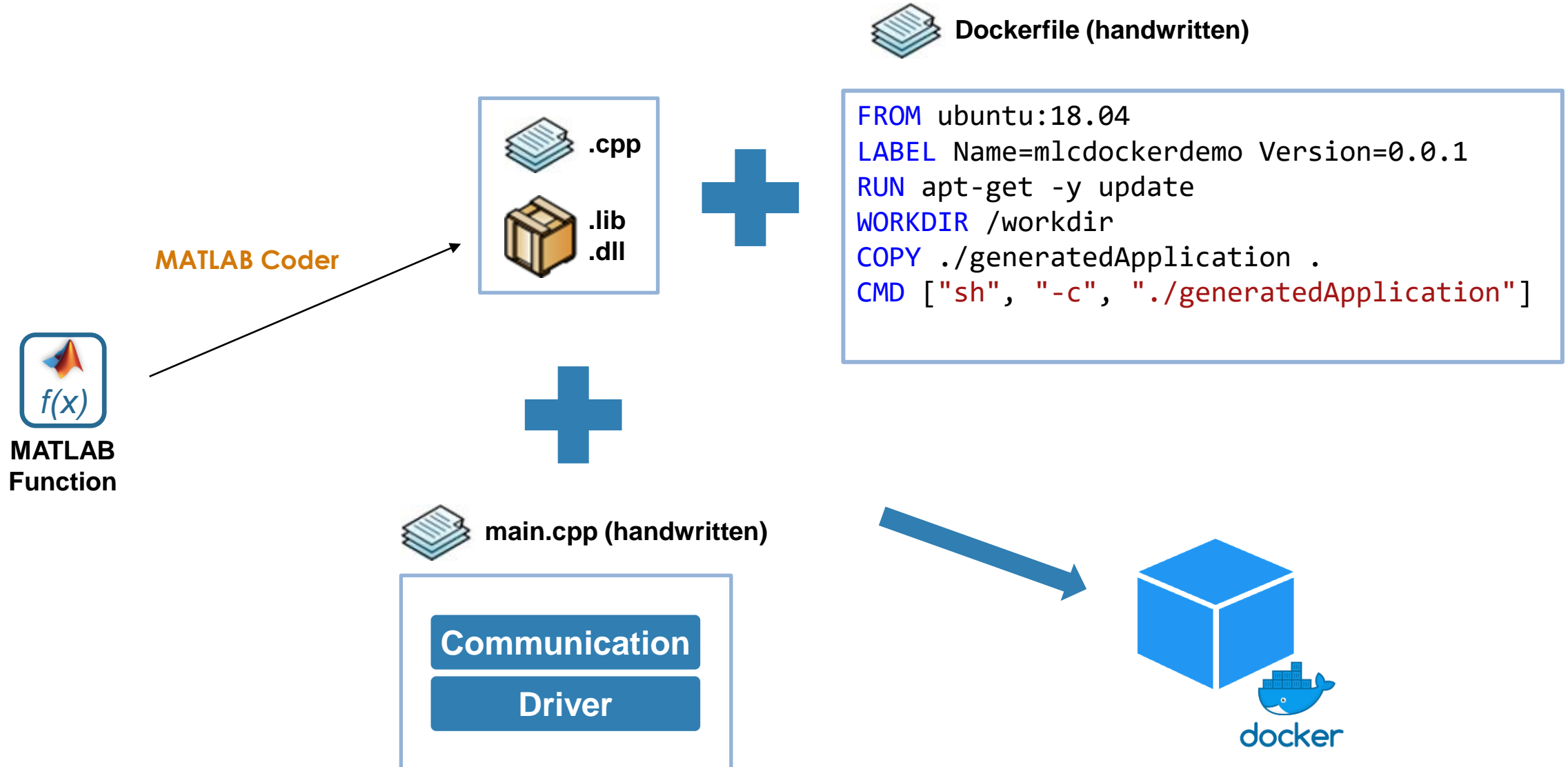
**Implement**  
algorithms on embedded processors



# Integrate Generated Code with Other Systems

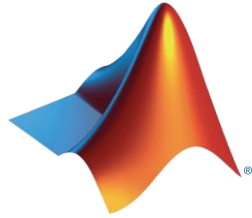


# Building a Container from Generated Code



# Example Python Bindings

```
function y = timestwo(x)
y = 2*x;
```



**coder-swig** on github:

<https://github.com/mathworks/coder-swig>

```
def main():
    "Main function to test timestwo generated code"
    from timestwoPython import timestwo

    # Call initialize function to set up state
    print "Calling initialize"
    timestwo.timestwo_initialize()
    input = 3.0;
    print "Input = {0:g}".format(input)

    #Call entry-point
    result = timestwo.timestwo(input)

    print "Result = {0:g}".format(result)

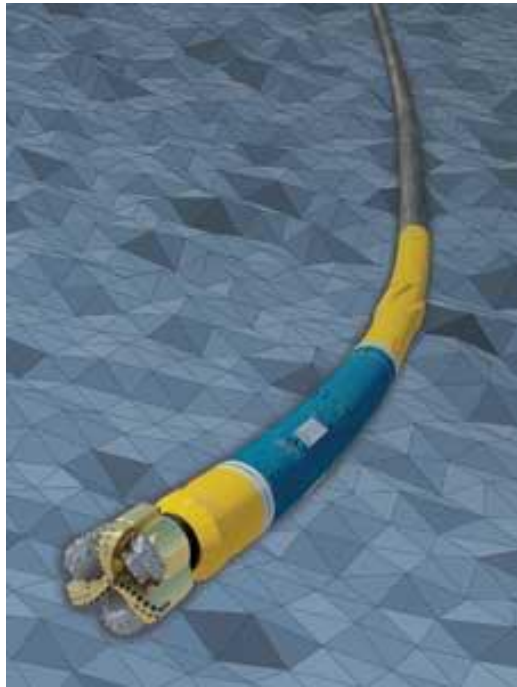
    # Call terminate function to perform clean up
    print "Calling terminate"
    timestwo.timestwo_terminate()

if __name__ == "__main__":
    main()
```



# Examples of MATLAB Coder Usage

**Integrate**  
algorithms with custom software



Baker Hughes



Qualcomm



dorsaVi

**Implement**  
algorithms on embedded processors



Idneo



Delphi

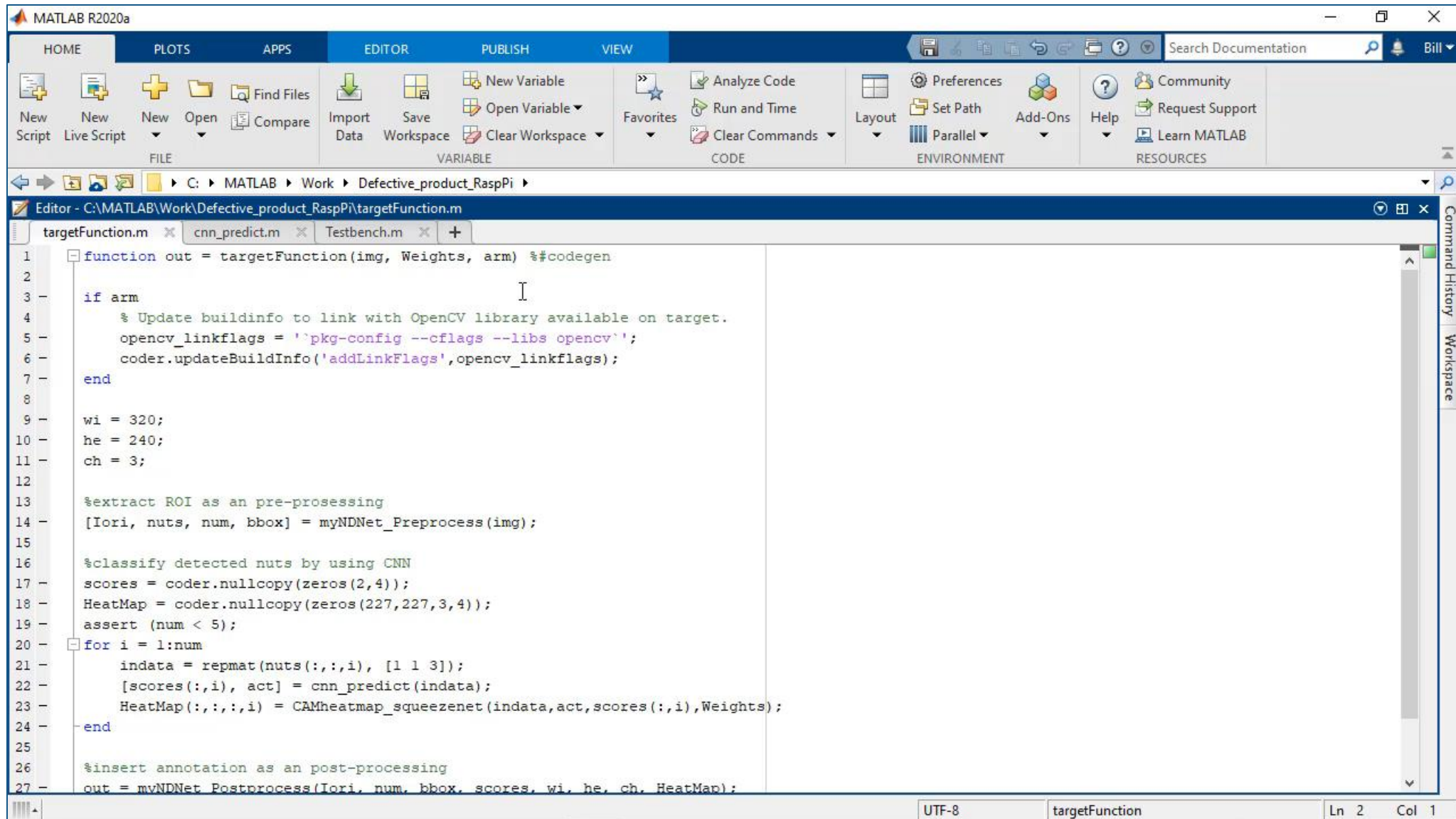


Respiri



# Deep Learning on Raspberry Pi Example

**Implement**  
algorithms on embedded processors



The image shows the MATLAB R2020a interface. The top toolbar includes tabs for HOME, PLOTS, APPS, EDITOR, PUBLISH, and VIEW. The EDITOR tab is active, showing a code editor with the file `targetFunction.m` open. The code is a function `targetFunction` that takes `img`, `Weights`, and `arm` as inputs and returns `out`. The function includes comments in Spanish and code for pre-processing, CNN classification, and post-processing. The code is as follows:

```
1 function out = targetFunction(img, Weights, arm) %#codegen
2
3 if arm
4     % Update buildinfo to link with OpenCV library available on target.
5     opencv_linkflags = 'pkg-config --cflags --libs opencv';
6     coder.updateBuildInfo('addLinkFlags', opencv_linkflags);
7 end
8
9 wi = 320;
10 he = 240;
11 ch = 3;
12
13 %extract ROI as an pre-processing
14 [Iori, nuts, num, bbox] = myNDNet_Preprocess(img);
15
16 %classify detected nuts by using CNN
17 scores = coder.nullcopy(zeros(2,4));
18 HeatMap = coder.nullcopy(zeros(227,227,3,4));
19 assert (num < 5);
20 for i = 1:num
21     indata = repmat(nuts(:, :, i), [1 1 3]);
22     [scores(:, i), act] = cnn_predict(indata);
23     HeatMap(:, :, :, i) = CAMheatmap_squeezenet(indata, act, scores(:, i), Weights);
24 end
25
26 %insert annotation as an post-processing
27 out = myNDNet_Postprocess(Iori, num, bbox, scores, wi, he, ch, HeatMap);
```

The bottom status bar shows the encoding is UTF-8, the file name is `targetFunction`, and the cursor is at line 2, column 1.



HOME PLOTS APPS EDITOR PUBLISH VIEW

New Script New Live Script New Open Find Files Compare Import Data Save Workspace Open Variable Clear Workspace Analyze Code Run and Time Clear Commands Favorites Layout Set Path Parallel Add-Ons Help Community Request Support Learn MATLAB

FILE VARIABLE CODE ENVIRONMENT RESOURCES

C:\MATLAB\Work\Defective\_product\_RaspPi

Editor - C:\MATLAB\Work\Defective\_product\_RaspPi\targetFunction.m

```
targetFunction.m x cnn_predict.m x Testbench.m x +
1 function out = targetFunction(img, Weights, arm) %#codegen
2
3 if arm
4     % Update buildinfo to link with OpenCV library available on target.
5     opencv_linkflags = 'pkg-config --cflags --libs opencv';
6     coder.updateBuildInfo('addLinkFlags', opencv_linkflags);
7 end
8
9 wi = 320;
10 he = 240;
11 ch = 3;
12
13 %extract ROI as an pre-processing
14 [Iori, nuts, num, bbox] = myNDNet_Preprocess(img);
15
16 %classify detected nuts by using CNN
17 scores = coder.nullcopy(zeros(2,4));
18 HeatMap = coder.nullcopy(zeros(227,227,3,4));
19 assert (num < 5);
20 for i = 1:num
21     indata = repmat(nuts(:,:,i), [1 1 3]);
22     [scores(:,i), act] = cnn_predict(indata);
23     HeatMap(:,:,:,i) = CAMheatmap_squeezenet(indata, act, scores(:,i), Weights);
24 end
25
26 %insert annotation as an post-processing
27 out = mvNDNet_Postprocess(Iori, num, bbox, scores, wi, he, ch, HeatMap);
```

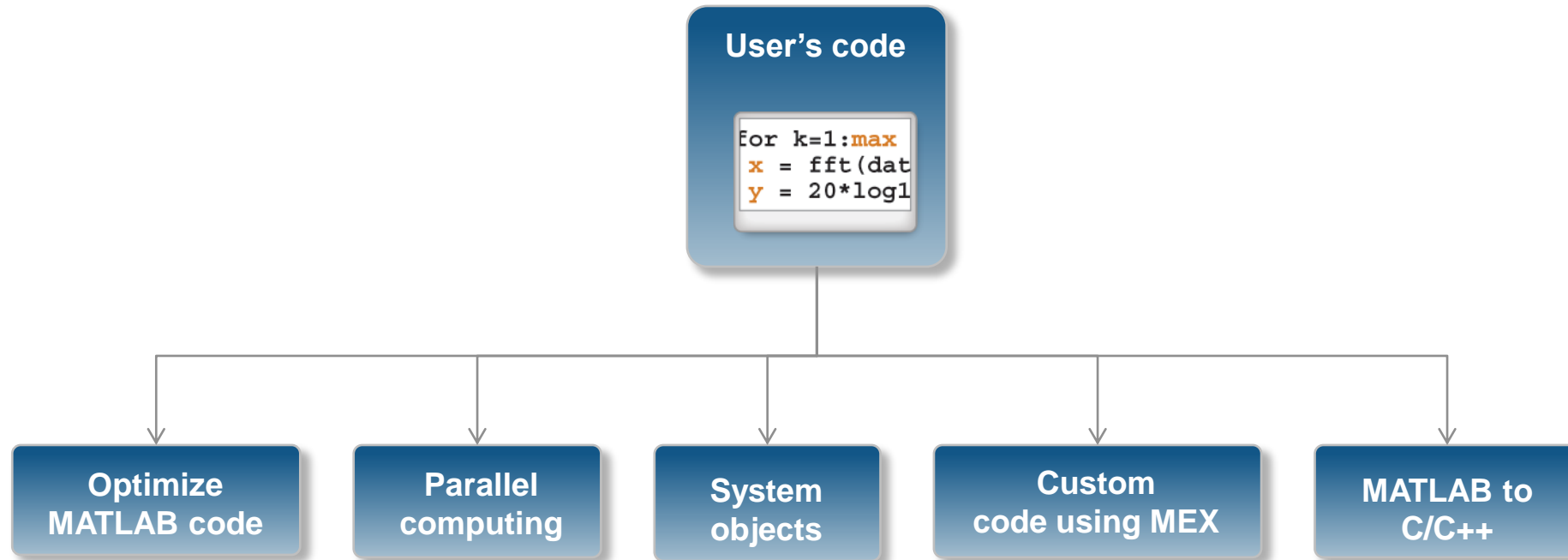
# Acceleration Strategies

**Accelerate**  
algorithm execution

- Better algorithms  
Matrix inversion vs. QR or SVD
  - Different approaches to solving the same problem
- More efficient implementation  
Hand-coded vs. optimized library (BLAS and LAPACK)
  - Different optimization of the same algorithm
- More computational resources  
Single-threaded vs. multithreaded (multithreaded BLAS)
  - Leveraging additional processors, cores, GPUs, FPGAs, etc.

# Accelerating Algorithm Execution

**Accelerate**  
algorithm execution



# Acceleration Using MEX

Accelerate  
algorithm execution

- Speed-up factor will vary
- When you **may** see a speedup:
  - Often for communications and signal processing
  - Always for fixed point
  - Likely for loops with states or when vectorization isn't possible
- When you **may not** see a speedup:
  - MATLAB implicitly multithreads computation.
  - Built-functions call IPP or BLAS libraries.

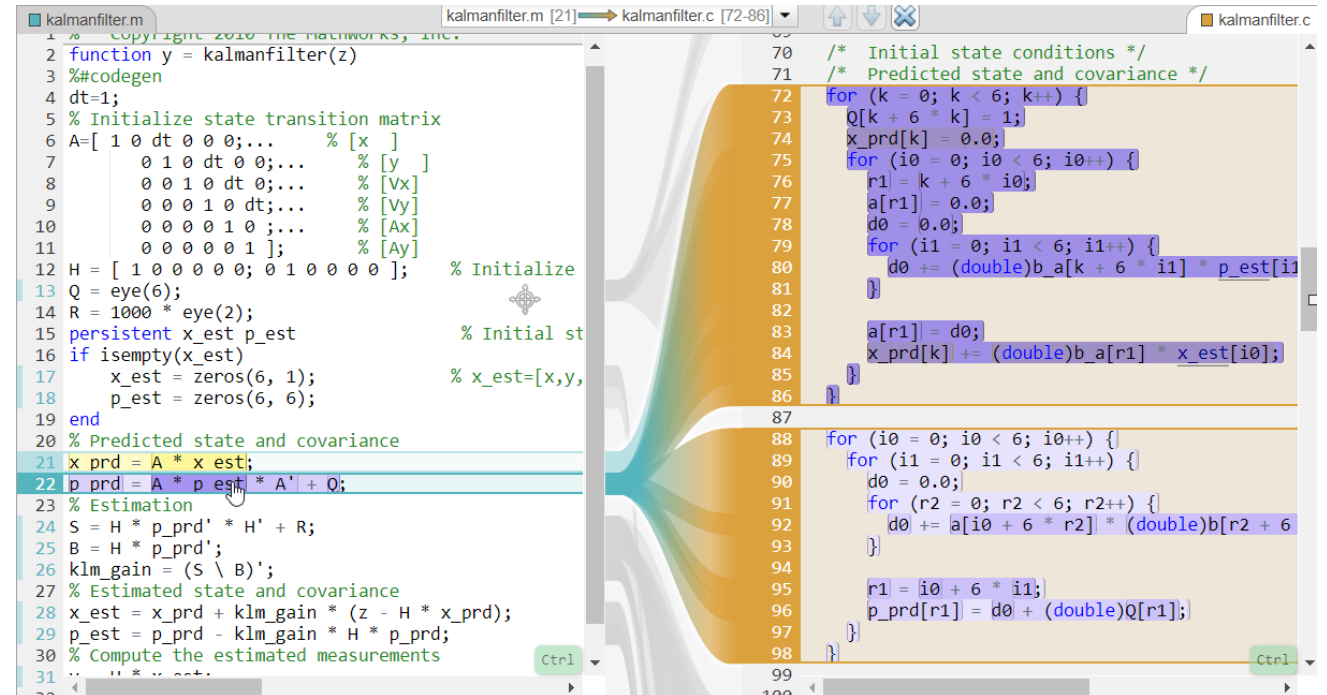
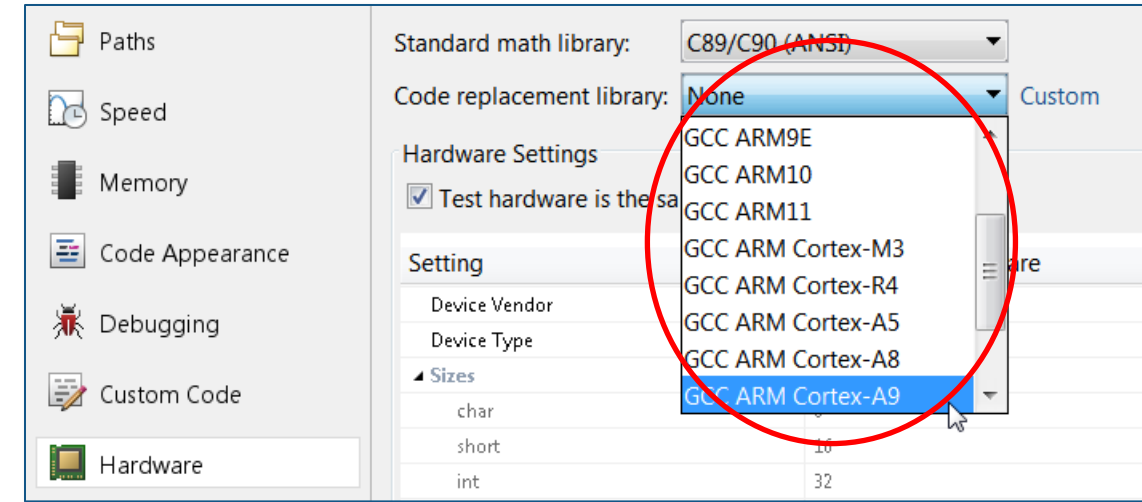
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# Working with Embedded Coder

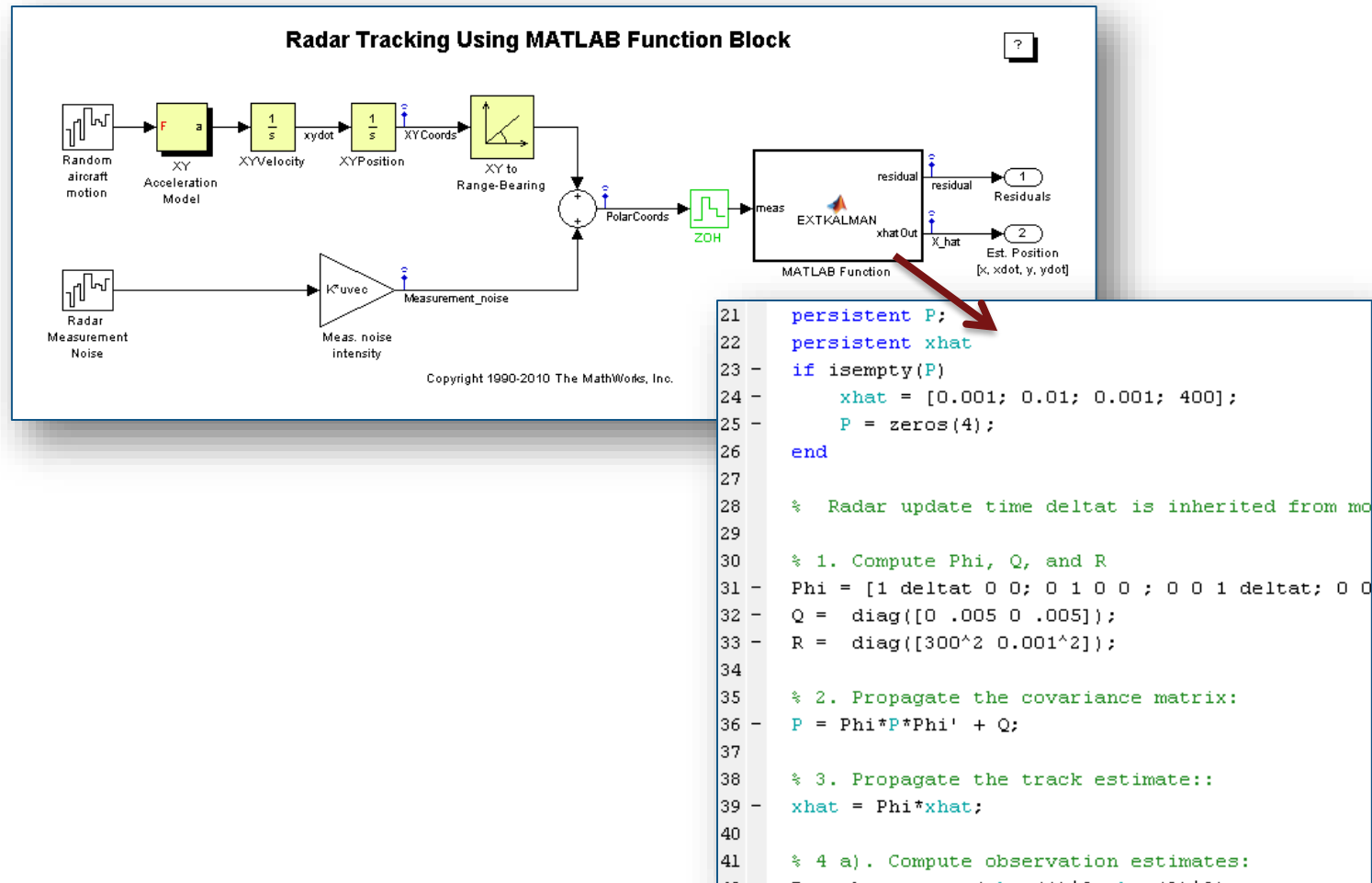
Advanced support for MATLAB Coder, including:

- Speed & Memory
- Hardware-specific optimization
- Code appearance
- Bidirectional traceability
- Software/Processor-in-the-loop verification
- Execution profiling



# Working with Simulink and Embedded Coder

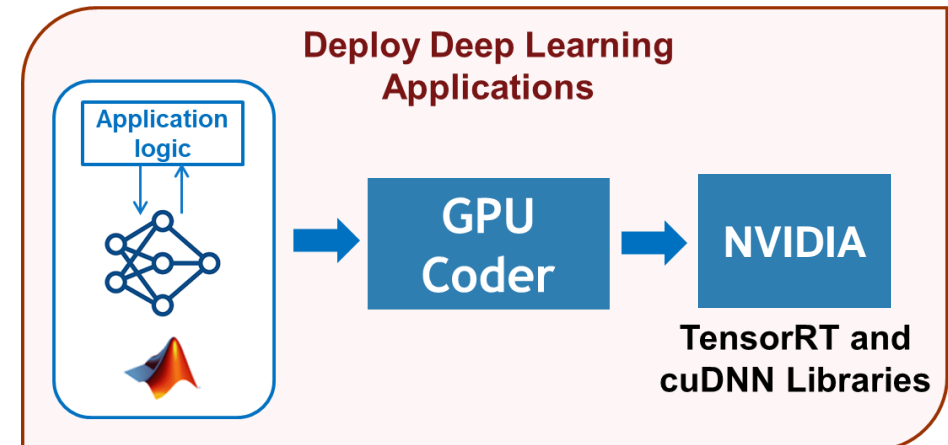
## MATLAB Function block in Simulink



# Working with GPU Coder

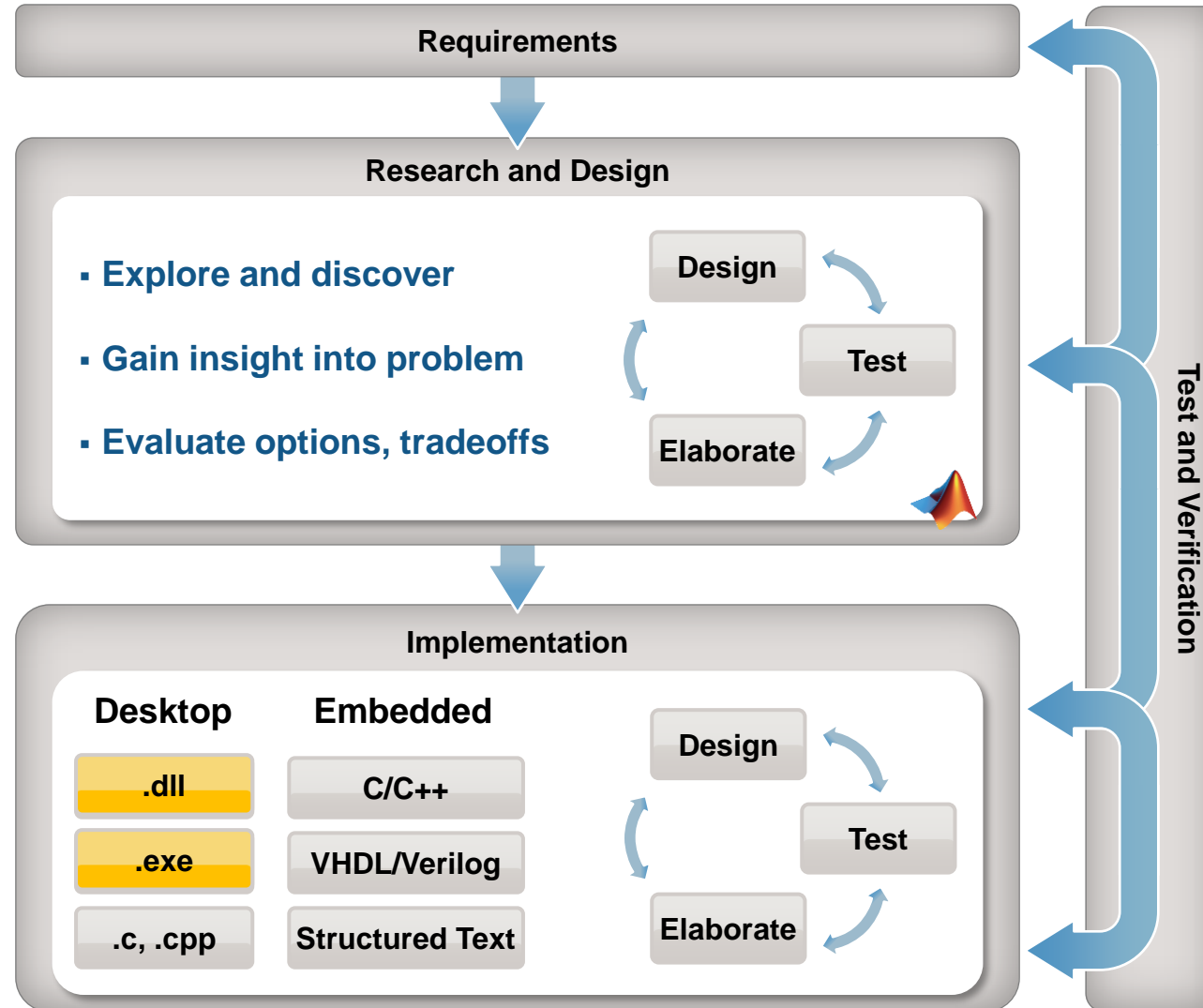
## Generate CUDA for NVIDIA GPUs

- Deploy deep learning applications, include pre- and post-processing
- Create CUDA kernels from MATLAB algorithms for acceleration on GPUs
- Automated deployment to NVIDIA GPUs, including Jetson/DRIVE

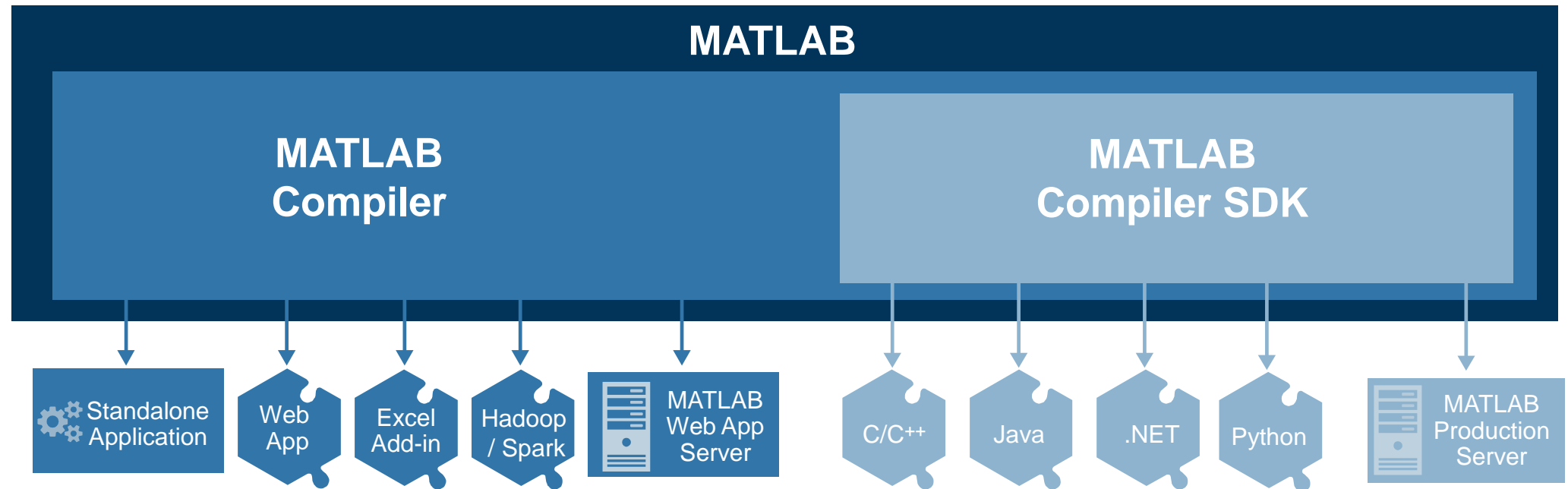




# Other Desktop Deployment Options



# Other Deployment Options



**MATLAB Compiler** for sharing MATLAB programs without integration programming

**MATLAB Web App Server** provides feature set to publish MATLAB apps and Simulink simulations created using App Designer as interactive web apps

**MATLAB Compiler SDK** provides implementation and platform flexibility for software developers

**MATLAB Production Server** provides the most efficient development path for secure and scalable web and enterprise applications

# Choosing the Right Deployment Solution



.c/cpp

**MATLAB Coder**



**MATLAB Compiler  
MATLAB Compiler SDK**

<b>Output</b>	Portable and readable C/C++ source code	Executable or software component/shared library
<b>Main Use Case</b>	Deploy MATLAB code as portable C/C++ code on embedded platforms or desktop	Deploy MATLAB programs as standalone applications on desktop or production servers
<b>MATLAB language support</b>	Subset	Full
<b>Supported toolboxes</b>	Some toolboxes	Most toolboxes
<b>Production</b>	Embedded Coder	MATLAB Production Server
<b>Graphics Support</b>	None	Full
<b>Library Dependency</b>	None	MATLAB Runtime

## More Information

- To learn more, visit the product page:  
[mathworks.com/products/matlab-coder](https://mathworks.com/products/matlab-coder)
  
- To request a trial license:
  - Talk to your MathWorks account manager to request a trial license and set up a guided evaluation with an application engineer